

**MAS156: Mathematics (Electrical and  
Aerospace)**  
**MAS161 (General Engineering  
Mathematics)**

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Monday 15th October 2018, 5pm  
Diamond LT4

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# Course matters

There is a Formula Sheet which can be used in exams (it is provided with the exam paper). You will find a copy of this on the webpage.

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Copies of exams from previous years are also on the site.

# Matrices

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Later in this course (Semester 2) we will spend a good amount of time studying *matrices*. However, they are so fundamental to engineering mathematics that they may have already appeared elsewhere in your course or could come up before we get to them. To help you to get comfortable in their use, we will cover some of the basics today.



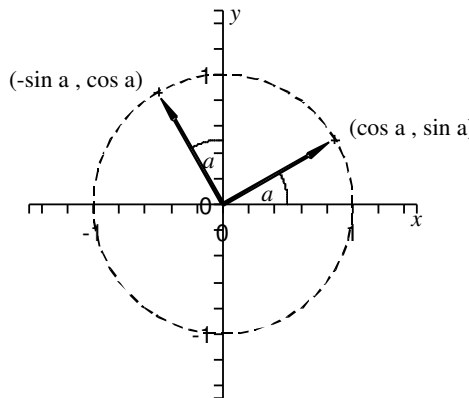
**Why matrices?**

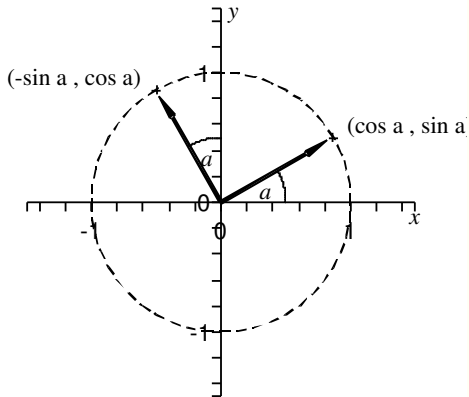
# Matrices as transformations

Let  $0 \leq a < 2\pi$  and consider the transformation of the plane given by anticlockwise rotation through the angle  $a$ , as shown below.

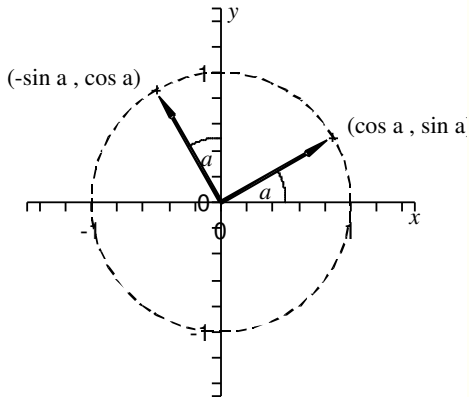
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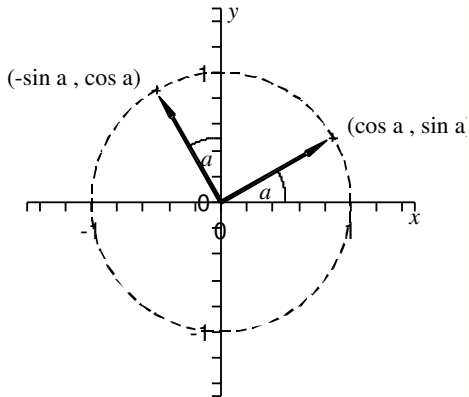




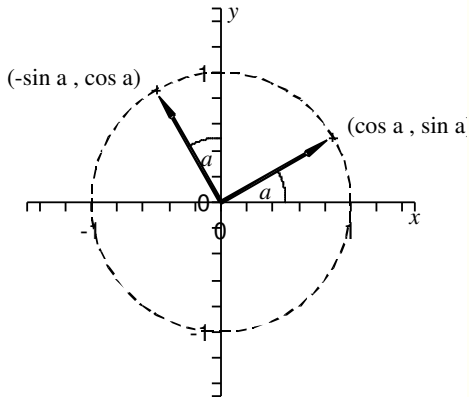
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Using geometry, we find that the point  $(1, 0)$  transforms to  $(\cos a, \sin a)$  and  $(0, 1)$  transforms to  $(-\sin a, \cos a)$ .

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It turns out that a general point  $(x, y)$  transforms to  $(x \cos a - y \sin a, x \sin a + y \cos a)$ , and this transformation is best described using a matrix.

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Once again, problems like these are best solved using matrices.

# Definitions

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We sometimes write  $A = (a_{ij})$  for the above matrix.

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is called the *identity matrix of size  $n$* .

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The identity matrix  $I_n$  is always *square*. That is, it has the same number of rows and columns.

# Matrix operations

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$$A + B = \begin{pmatrix} a_{11} + b_{11} & a_{12} + b_{12} & \dots & a_{1n} + b_{1n} \\ a_{21} + b_{21} & a_{22} + b_{22} & \dots & a_{2n} + b_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} + b_{m1} & a_{m2} + b_{m2} & \dots & a_{mn} + b_{mn} \end{pmatrix}.$$

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In other words, to add two matrices *of the same dimensions* simply add their entries componentwise.

For example,

$$\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix} + \begin{pmatrix} 2 & 0 & 3 \\ 4 & 2 & 0 \end{pmatrix} =$$

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# Warning!

It is not possible to add two matrices if their dimensions are different, so take care!

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That is, if  $A$  is  $p \times q$  and  $B$  is  $q \times r$ , then we can find their product. The result,  $AB$ , is a  $p \times r$  matrix.

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# Column vectors

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One case that occurs frequently is when the second matrix is a *column vector* (i.e. an  $n \times 1$  matrix) of a suitable length. For example,

$$\begin{pmatrix} 1 & 3 & 1 \\ 2 & 0 & -1 \end{pmatrix} \begin{pmatrix} 3 \\ 2 \\ 2 \end{pmatrix} = \begin{pmatrix} 1.3 + 3.2 + 1.2 \\ 2.3 + 0.2 + (-1).2 \end{pmatrix} =$$



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**Activity.** Working in groups of two or three, in each case find a matrix  $A$  such that

$$(i) \quad A \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} x \cos a - y \sin a \\ x \sin a + y \cos a \end{pmatrix}.$$

$$(ii) \quad A \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} x - 2y + z \\ 2y - 8z \\ -4x + 5y + 9z \end{pmatrix}.$$

$$(iii) \quad A \begin{pmatrix} x_{\text{urban}} \\ x_{\text{suburban}} \end{pmatrix} = \begin{pmatrix} 0.95x_{\text{urban}} + 0.03x_{\text{suburban}} \\ 0.05x_{\text{urban}} + 0.97x_{\text{suburban}} \end{pmatrix}.$$

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This matrix corresponds to rotation of the plane through an angle  $a$ : given a point  $(x, y)$ , calculating

$$A \begin{pmatrix} x \\ y \end{pmatrix}$$

gives the coordinates of where it ends up after the rotation.

$$(ii) \quad A = \begin{pmatrix} 1 & -2 & 1 \\ 0 & 2 & -8 \\ -4 & 5 & 9 \end{pmatrix}.$$

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Notice that the equations in the example at the start of the lecture correspond to the matrix equation

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$$A \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 0 \\ 8 \\ -9 \end{pmatrix}.$$

The solution is then

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} = A^{-1} \begin{pmatrix} 0 \\ 8 \\ -9 \end{pmatrix}.$$



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In the example at the beginning of the lecture,

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will give the amount of people in the urban and suburban areas after one year. Multiplying by  $A$  repeatedly means the populations after 25 years will be given by

$$A^{25} \begin{pmatrix} 600,000 \\ 400,000 \end{pmatrix}.$$

**And finally. . .**

## Reminders:

- email address [mas-engineering@sheffield.ac.uk](mailto:mas-engineering@sheffield.ac.uk)
- website <http://engmaths.group.shef.ac.uk/mas156>  
<http://engmaths.group.shef.ac.uk/mas161> (also accessible through MOLE).