

MAS156: Mathematics (Electrical and Aerospace)

Dr Sam Marsh

mas-engineering@sheffield.ac.uk

Tuesday 16th October 2018, 1pm
Diamond LT4

Course matters

There is a Formula Sheet which can be used in exams (it is provided with the exam paper). You will find a copy of this on the webpage.

There is a Formula Sheet which can be used in exams (it is provided with the exam paper). You will find a copy of this on the webpage.

Copies of exams from previous years are also on the site.

Matrices

Later in this course (Semester 2) we will spend a good amount of time studying *matrices*.

Later in this course (Semester 2) we will spend a good amount of time studying *matrices*. However, they are so fundamental to engineering mathematics that they may have already appeared elsewhere in your course or could come up before we get to them.

Later in this course (Semester 2) we will spend a good amount of time studying *matrices*. However, they are so fundamental to engineering mathematics that they may have already appeared elsewhere in your course or could come up before we get to them. To help you to get comfortable in their use, we will cover some of the basics today.

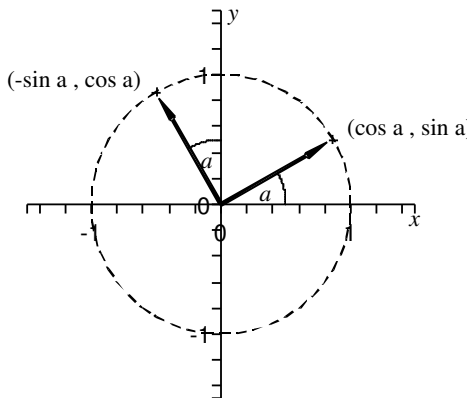
Why matrices?

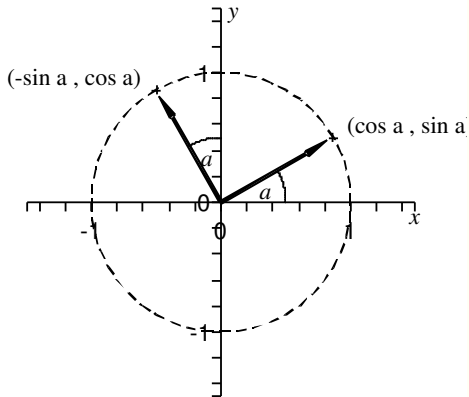
Matrices as transformations

Let $0 \leq a < 2\pi$ and consider the transformation of the plane given by anticlockwise rotation through the angle a , as shown below.

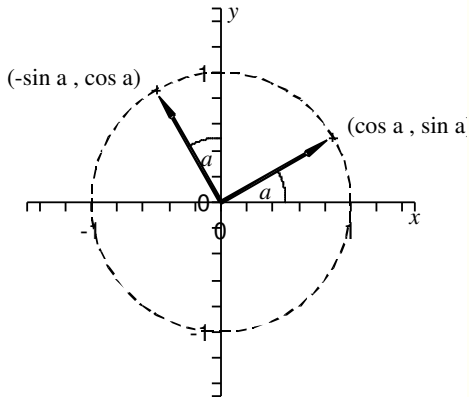
Matrices as transformations

Let $0 \leq a < 2\pi$ and consider the transformation of the plane given by anticlockwise rotation through the angle a , as shown below.

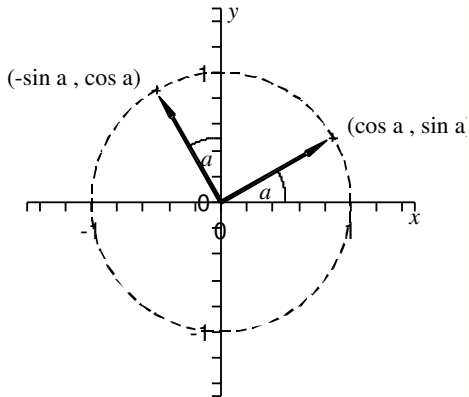




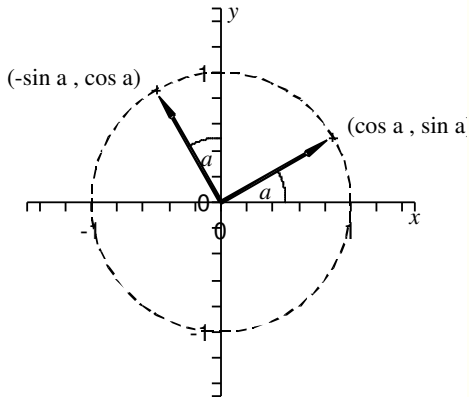
Using geometry, we find that the point $(1, 0)$ transforms to



Using geometry, we find that the point $(1, 0)$ transforms to $(\cos a, \sin a)$



Using geometry, we find that the point $(1, 0)$ transforms to $(\cos a, \sin a)$ and $(0, 1)$ transforms to



Using geometry, we find that the point $(1, 0)$ transforms to $(\cos a, \sin a)$ and $(0, 1)$ transforms to $(-\sin a, \cos a)$.

It turns out that a general point (x, y) transforms to

It turns out that a general point (x, y) transforms to $(x \cos a - y \sin a, x \sin a + y \cos a)$,

It turns out that a general point (x, y) transforms to $(x \cos a - y \sin a, x \sin a + y \cos a)$, and this transformation is best described using a matrix.

Matrices to solve equations

Many engineering problems involve finding the solution of systems of equations.

Matrices to solve equations

Many engineering problems involve finding the solution of systems of equations.

Consider the system of equations

$$\begin{array}{rcccccc} x & - & 2y & + & z & = & 0 \\ & & 2y & - & 8z & = & 8 \\ -4x & + & 5y & + & 9z & = & -9. \end{array}$$

Matrices to solve equations

Many engineering problems involve finding the solution of systems of equations.

Consider the system of equations

$$\begin{aligned}x - 2y + z &= 0 \\2y - 8z &= 8 \\-4x + 5y + 9z &= -9.\end{aligned}$$

We want to find values of x , y and z that satisfy all three of these equations.

Matrices to solve equations

Many engineering problems involve finding the solution of systems of equations.

Consider the system of equations

$$\begin{array}{rccccrcr} x & - & 2y & + & z & = & 0 \\ & & 2y & - & 8z & = & 8 \\ -4x & + & 5y & + & 9z & = & -9. \end{array}$$

We want to find values of x , y and z that satisfy all three of these equations.

By adding and subtracting multiples of the equations from each other,

Matrices to solve equations

Many engineering problems involve finding the solution of systems of equations.

Consider the system of equations

$$\begin{array}{rcccccc} x & - & 2y & + & z & = & 0 \\ & & 2y & - & 8z & = & 8 \\ -4x & + & 5y & + & 9z & = & -9. \end{array}$$

We want to find values of x , y and z that satisfy all three of these equations.

By adding and subtracting multiples of the equations from each other, we find that the solution is $x = 29$, $y = 16$ and $z = 3$.

Matrices to solve equations

Many engineering problems involve finding the solution of systems of equations.

Consider the system of equations

$$\begin{array}{rccccrcr} x & - & 2y & + & z & = & 0 \\ & & 2y & - & 8z & = & 8 \\ -4x & + & 5y & + & 9z & = & -9. \end{array}$$

We want to find values of x , y and z that satisfy all three of these equations.

By adding and subtracting multiples of the equations from each other, we find that the solution is $x = 29$, $y = 16$ and $z = 3$. We will later see that there is a systematic approach to solving such systems,

Matrices to solve equations

Many engineering problems involve finding the solution of systems of equations.

Consider the system of equations

$$\begin{array}{rcccccc} x & - & 2y & + & z & = & 0 \\ & & 2y & - & 8z & = & 8 \\ -4x & + & 5y & + & 9z & = & -9. \end{array}$$

We want to find values of x , y and z that satisfy all three of these equations.

By adding and subtracting multiples of the equations from each other, we find that the solution is $x = 29$, $y = 16$ and $z = 3$. We will later see that there is a systematic approach to solving such systems, again using matrices.

Matrices to model systems

A certain city consists of an urban area and suburbs.

Matrices to model systems

A certain city consists of an urban area and suburbs. Each year 5% of those living in the urban area move to the suburbs

Matrices to model systems

A certain city consists of an urban area and suburbs. Each year 5% of those living in the urban area move to the suburbs and 3% of those living in the suburbs move to the urban area.

Matrices to model systems

A certain city consists of an urban area and suburbs. Each year 5% of those living in the urban area move to the suburbs and 3% of those living in the suburbs move to the urban area. If there are initially 600,000 people in the urban area and 400,000 in the suburbs, how many are in each 25 years later?

Matrices to model systems

A certain city consists of an urban area and suburbs. Each year 5% of those living in the urban area move to the suburbs and 3% of those living in the suburbs move to the urban area. If there are initially 600,000 people in the urban area and 400,000 in the suburbs, how many are in each 25 years later?
Once again, problems like these are best solved using matrices.

Definitions

Let m and n be positive integers.

Let m and n be positive integers. Then an $m \times n$ *matrix* A is an array of real numbers, with m rows and n columns;

Let m and n be positive integers. Then an $m \times n$ *matrix* A is an array of real numbers, with m rows and n columns; that is

Let m and n be positive integers. Then an $m \times n$ *matrix* A is an array of real numbers, with m rows and n columns; that is

$$A = \begin{pmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{pmatrix}$$

Let m and n be positive integers. Then an $m \times n$ *matrix* A is an array of real numbers, with m rows and n columns; that is

$$A = \begin{pmatrix} a_{11} & a_{12} & \dots & a_{1n} \\ a_{21} & a_{22} & \dots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \dots & a_{mn} \end{pmatrix}$$

We sometimes write $A = (a_{ij})$ for the above matrix.

For example,

For example,

$$\begin{pmatrix} 3 & 1 & 2 \\ 0 & 2 & 1 \end{pmatrix}$$

For example,

$\begin{pmatrix} 3 & 1 & 2 \\ 0 & 2 & 1 \end{pmatrix}$ is a 2×3 matrix,

For example,

$\begin{pmatrix} 3 & 1 & 2 \\ 0 & 2 & 1 \end{pmatrix}$ is a 2×3 matrix, and

For example,

$\begin{pmatrix} 3 & 1 & 2 \\ 0 & 2 & 1 \end{pmatrix}$ is a 2×3 matrix, and

$$\begin{pmatrix} 2\sqrt{2} & 7 \\ 0 & 1 \\ 3 & 4 - \sqrt{2} \\ 7 & 7 \end{pmatrix}$$

For example,

$\begin{pmatrix} 3 & 1 & 2 \\ 0 & 2 & 1 \end{pmatrix}$ is a 2×3 matrix, and

$\begin{pmatrix} 2\sqrt{2} & 7 \\ 0 & 1 \\ 3 & 4 - \sqrt{2} \\ 7 & 7 \end{pmatrix}$ is a 4×2 matrix.

Identity matrices

Let n be a positive integer.

Identity matrices

Let n be a positive integer. Then the $n \times n$ matrix I_n given by

Identity matrices

Let n be a positive integer. Then the $n \times n$ matrix I_n given by

$$I_n = \begin{pmatrix} 1 & 0 & \dots & 0 \\ 0 & 1 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & 1 \end{pmatrix}$$

Identity matrices

Let n be a positive integer. Then the $n \times n$ matrix I_n given by

$$I_n = \begin{pmatrix} 1 & 0 & \dots & 0 \\ 0 & 1 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & 1 \end{pmatrix}$$

is called the *identity matrix of size n* .

For example,

For example,

$$I_2 = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

For example,

$$I_2 = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \quad \text{and} \quad I_3 = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}.$$

For example,

$$I_2 = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \quad \text{and} \quad I_3 = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}.$$

The identity matrix I_n is always *square*.

For example,

$$I_2 = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \quad \text{and} \quad I_3 = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}.$$

The identity matrix I_n is always *square*. That is, it has the same number of rows and columns.

Matrix operations

To use matrices we have to define some basic mathematical operations.

To use matrices we have to define some basic mathematical operations. Two basic operations are matrix addition

To use matrices we have to define some basic mathematical operations. Two basic operations are matrix addition and scalar multiplication.

Matrix addition

Let $A = (a_{ij})$ and $B = (b_{ij})$ both be $m \times n$ matrices.

Matrix addition

Let $A = (a_{ij})$ and $B = (b_{ij})$ both be $m \times n$ matrices. Then we define the sum of A and B by

Matrix addition

Let $A = (a_{ij})$ and $B = (b_{ij})$ both be $m \times n$ matrices. Then we define the sum of A and B by

$$A + B = \begin{pmatrix} a_{11} + b_{11} & a_{12} + b_{12} & \dots & a_{1n} + b_{1n} \\ a_{21} + b_{21} & a_{22} + b_{22} & \dots & a_{2n} + b_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} + b_{m1} & a_{m2} + b_{m2} & \dots & a_{mn} + b_{mn} \end{pmatrix}.$$

Matrix addition

Let $A = (a_{ij})$ and $B = (b_{ij})$ both be $m \times n$ matrices. Then we define the sum of A and B by

$$A + B = \begin{pmatrix} a_{11} + b_{11} & a_{12} + b_{12} & \dots & a_{1n} + b_{1n} \\ a_{21} + b_{21} & a_{22} + b_{22} & \dots & a_{2n} + b_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} + b_{m1} & a_{m2} + b_{m2} & \dots & a_{mn} + b_{mn} \end{pmatrix}.$$

In other words, to add two matrices *of the same dimensions*

Matrix addition

Let $A = (a_{ij})$ and $B = (b_{ij})$ both be $m \times n$ matrices. Then we define the sum of A and B by

$$A + B = \begin{pmatrix} a_{11} + b_{11} & a_{12} + b_{12} & \dots & a_{1n} + b_{1n} \\ a_{21} + b_{21} & a_{22} + b_{22} & \dots & a_{2n} + b_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} + b_{m1} & a_{m2} + b_{m2} & \dots & a_{mn} + b_{mn} \end{pmatrix}.$$

In other words, to add two matrices *of the same dimensions* simply add their entries componentwise.

For example,

$$\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix} + \begin{pmatrix} 2 & 0 & 3 \\ 4 & 2 & 0 \end{pmatrix} =$$

For example,

$$\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix} + \begin{pmatrix} 2 & 0 & 3 \\ 4 & 2 & 0 \end{pmatrix} = \begin{pmatrix} 3 & 0 & 3 \\ 4 & 3 & 0 \end{pmatrix}.$$

Warning!

It is not possible to add two matrices if their dimensions are different, so take care!

Scalar multiplication

Let $A = (a_{ij})$ be an $m \times n$ matrix and let k be a real number.

Scalar multiplication

Let $A = (a_{ij})$ be an $m \times n$ matrix and let k be a real number.
(We refer to k here as a *scalar*.)

Scalar multiplication

Let $A = (a_{ij})$ be an $m \times n$ matrix and let k be a real number. (We refer to k here as a *scalar*.) Then we define

Scalar multiplication

Let $A = (a_{ij})$ be an $m \times n$ matrix and let k be a real number. (We refer to k here as a *scalar*.) Then we define

$$kA = \begin{pmatrix} ka_{11} & ka_{12} & \dots & ka_{1n} \\ ka_{21} & ka_{22} & \dots & ka_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ ka_{m1} & ka_{m2} & \dots & ka_{mn} \end{pmatrix}.$$

Scalar multiplication

Let $A = (a_{ij})$ be an $m \times n$ matrix and let k be a real number. (We refer to k here as a *scalar*.) Then we define

$$kA = \begin{pmatrix} ka_{11} & ka_{12} & \dots & ka_{1n} \\ ka_{21} & ka_{22} & \dots & ka_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ ka_{m1} & ka_{m2} & \dots & ka_{mn} \end{pmatrix}.$$

In other words, to multiply a matrix by a scalar, k ,

Scalar multiplication

Let $A = (a_{ij})$ be an $m \times n$ matrix and let k be a real number. (We refer to k here as a *scalar*.) Then we define

$$kA = \begin{pmatrix} ka_{11} & ka_{12} & \dots & ka_{1n} \\ ka_{21} & ka_{22} & \dots & ka_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ ka_{m1} & ka_{m2} & \dots & ka_{mn} \end{pmatrix}.$$

In other words, to multiply a matrix by a scalar, k , simply multiply each entry of the matrix by k .

For example,

$$3 \begin{pmatrix} 1 & 3 \\ -1 & 2 \end{pmatrix} =$$

For example,

$$3 \begin{pmatrix} 1 & 3 \\ -1 & 2 \end{pmatrix} = \begin{pmatrix} 3 & 9 \\ -3 & 6 \end{pmatrix}$$

For example,

$$3 \begin{pmatrix} 1 & 3 \\ -1 & 2 \end{pmatrix} = \begin{pmatrix} 3 & 9 \\ -3 & 6 \end{pmatrix}$$

and

For example,

$$3 \begin{pmatrix} 1 & 3 \\ -1 & 2 \end{pmatrix} = \begin{pmatrix} 3 & 9 \\ -3 & 6 \end{pmatrix}$$

and

$$0 \begin{pmatrix} 1 & 0 & 2 & 0 & 0 \\ 0 & 1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 3 \end{pmatrix} =$$

For example,

$$3 \begin{pmatrix} 1 & 3 \\ -1 & 2 \end{pmatrix} = \begin{pmatrix} 3 & 9 \\ -3 & 6 \end{pmatrix}$$

and

$$0 \begin{pmatrix} 1 & 0 & 2 & 0 & 0 \\ 0 & 1 & 1 & 0 & 0 \\ 0 & 0 & 0 & 1 & 3 \end{pmatrix} = \begin{pmatrix} 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{pmatrix}.$$

Matrix multiplication

A big reason why matrices are so useful comes down to the rule for how they multiply.

A big reason why matrices are so useful comes down to the rule for how they multiply. This rule is not as straightforward as the rules for addition and scalar multiplication,

A big reason why matrices are so useful comes down to the rule for how they multiply. This rule is not as straightforward as the rules for addition and scalar multiplication, but is not too hard.

A big reason why matrices are so useful comes down to the rule for how they multiply. This rule is not as straightforward as the rules for addition and scalar multiplication, but is not too hard.

Matrices can only be multiplied when the dimensions match up in the right way.

A big reason why matrices are so useful comes down to the rule for how they multiply. This rule is not as straightforward as the rules for addition and scalar multiplication, but is not too hard.

Matrices can only be multiplied when the dimensions match up in the right way. The thing to remember is that the number of columns of the first matrix must be the same as the number of rows of the second one.

A big reason why matrices are so useful comes down to the rule for how they multiply. This rule is not as straightforward as the rules for addition and scalar multiplication, but is not too hard.

Matrices can only be multiplied when the dimensions match up in the right way. The thing to remember is that the number of columns of the first matrix must be the same as the number of rows of the second one.

That is, if A is $p \times q$ and B is $q \times r$,

A big reason why matrices are so useful comes down to the rule for how they multiply. This rule is not as straightforward as the rules for addition and scalar multiplication, but is not too hard.

Matrices can only be multiplied when the dimensions match up in the right way. The thing to remember is that the number of columns of the first matrix must be the same as the number of rows of the second one.

That is, if A is $p \times q$ and B is $q \times r$, then we can find their product.

A big reason why matrices are so useful comes down to the rule for how they multiply. This rule is not as straightforward as the rules for addition and scalar multiplication, but is not too hard.

Matrices can only be multiplied when the dimensions match up in the right way. The thing to remember is that the number of columns of the first matrix must be the same as the number of rows of the second one.

That is, if A is $p \times q$ and B is $q \times r$, then we can find their product. The result, AB , is a $p \times r$ matrix.

We illustrate the procedure with an example.

We illustrate the procedure with an example. Let

$$A = \begin{pmatrix} 1 & 2 & 3 \\ 0 & 1 & 1 \end{pmatrix} \quad \text{and} \quad B = \begin{pmatrix} 2 & 0 \\ 3 & 4 \\ 2 & 0 \end{pmatrix}$$

We illustrate the procedure with an example. Let

$$A = \begin{pmatrix} 1 & 2 & 3 \\ 0 & 1 & 1 \end{pmatrix} \quad \text{and} \quad B = \begin{pmatrix} 2 & 0 \\ 3 & 4 \\ 2 & 0 \end{pmatrix}$$

To find AB , we take each row from A

We illustrate the procedure with an example. Let

$$A = \begin{pmatrix} 1 & 2 & 3 \\ 0 & 1 & 1 \end{pmatrix} \quad \text{and} \quad B = \begin{pmatrix} 2 & 0 \\ 3 & 4 \\ 2 & 0 \end{pmatrix}$$

To find AB , we take each row from A (starting from the top)

We illustrate the procedure with an example. Let

$$A = \begin{pmatrix} 1 & 2 & 3 \\ 0 & 1 & 1 \end{pmatrix} \quad \text{and} \quad B = \begin{pmatrix} 2 & 0 \\ 3 & 4 \\ 2 & 0 \end{pmatrix}$$

To find AB , we take each row from A (starting from the top) and 'multiply it' by each column from B

We illustrate the procedure with an example. Let

$$A = \begin{pmatrix} 1 & 2 & 3 \\ 0 & 1 & 1 \end{pmatrix} \quad \text{and} \quad B = \begin{pmatrix} 2 & 0 \\ 3 & 4 \\ 2 & 0 \end{pmatrix}$$

To find AB , we take each row from A (starting from the top) and 'multiply it' by each column from B (starting from the left)

We illustrate the procedure with an example. Let

$$A = \begin{pmatrix} 1 & 2 & 3 \\ 0 & 1 & 1 \end{pmatrix} \quad \text{and} \quad B = \begin{pmatrix} 2 & 0 \\ 3 & 4 \\ 2 & 0 \end{pmatrix}$$

To find AB , we take each row from A (starting from the top) and 'multiply it' by each column from B (starting from the left) in the following way:

We illustrate the procedure with an example. Let

$$A = \begin{pmatrix} 1 & 2 & 3 \\ 0 & 1 & 1 \end{pmatrix} \quad \text{and} \quad B = \begin{pmatrix} 2 & 0 \\ 3 & 4 \\ 2 & 0 \end{pmatrix}$$

To find AB , we take each row from A (starting from the top) and 'multiply it' by each column from B (starting from the left) in the following way:

$$AB =$$

We illustrate the procedure with an example. Let

$$A = \begin{pmatrix} 1 & 2 & 3 \\ 0 & 1 & 1 \end{pmatrix} \quad \text{and} \quad B = \begin{pmatrix} 2 & 0 \\ 3 & 4 \\ 2 & 0 \end{pmatrix}$$

To find AB , we take each row from A (starting from the top) and 'multiply it' by each column from B (starting from the left) in the following way:

$$AB = \begin{pmatrix} 1 \cdot 2 + 2 \cdot 3 + 3 \cdot 2 \end{pmatrix}$$

We illustrate the procedure with an example. Let

$$A = \begin{pmatrix} 1 & 2 & 3 \\ 0 & 1 & 1 \end{pmatrix} \quad \text{and} \quad B = \begin{pmatrix} 2 & 0 \\ 3 & 4 \\ 2 & 0 \end{pmatrix}$$

To find AB , we take each row from A (starting from the top) and 'multiply it' by each column from B (starting from the left) in the following way:

$$AB = \begin{pmatrix} 1 \cdot 2 + 2 \cdot 3 + 3 \cdot 2 & 1 \cdot 0 + 2 \cdot 4 + 3 \cdot 0 \end{pmatrix}$$

We illustrate the procedure with an example. Let

$$A = \begin{pmatrix} 1 & 2 & 3 \\ 0 & 1 & 1 \end{pmatrix} \quad \text{and} \quad B = \begin{pmatrix} 2 & 0 \\ 3 & 4 \\ 2 & 0 \end{pmatrix}$$

To find AB , we take each row from A (starting from the top) and 'multiply it' by each column from B (starting from the left) in the following way:

$$AB = \begin{pmatrix} 1.2 + 2.3 + 3.2 & 1.0 + 2.4 + 3.0 \\ 0.2 + 1.3 + 1.2 \end{pmatrix}$$

We illustrate the procedure with an example. Let

$$A = \begin{pmatrix} 1 & 2 & 3 \\ 0 & 1 & 1 \end{pmatrix} \quad \text{and} \quad B = \begin{pmatrix} 2 & 0 \\ 3 & 4 \\ 2 & 0 \end{pmatrix}$$

To find AB , we take each row from A (starting from the top) and 'multiply it' by each column from B (starting from the left) in the following way:

$$AB = \begin{pmatrix} 1.2 + 2.3 + 3.2 & 1.0 + 2.4 + 3.0 \\ 0.2 + 1.3 + 1.2 & 0.0 + 1.4 + 1.0 \end{pmatrix} =$$

We illustrate the procedure with an example. Let

$$A = \begin{pmatrix} 1 & 2 & 3 \\ 0 & 1 & 1 \end{pmatrix} \quad \text{and} \quad B = \begin{pmatrix} 2 & 0 \\ 3 & 4 \\ 2 & 0 \end{pmatrix}$$

To find AB , we take each row from A (starting from the top) and 'multiply it' by each column from B (starting from the left) in the following way:

$$AB = \begin{pmatrix} 1 \cdot 2 + 2 \cdot 3 + 3 \cdot 2 & 1 \cdot 0 + 2 \cdot 4 + 3 \cdot 0 \\ 0 \cdot 2 + 1 \cdot 3 + 1 \cdot 2 & 0 \cdot 0 + 1 \cdot 4 + 1 \cdot 0 \end{pmatrix} = \begin{pmatrix} 14 & 8 \\ 5 & 4 \end{pmatrix}.$$

In the previous example, A is 2×3 and B is 3×2

In the previous example, A is 2×3 and B is 3×2 and the result is 2×2 .

In the previous example, A is 2×3 and B is 3×2 and the result is 2×2 . Of course, BA will not be the same matrix,

In the previous example, A is 2×3 and B is 3×2 and the result is 2×2 . Of course, BA will not be the same matrix, as the result will be 3×3 .

Column vectors

One case that occurs frequently is when the second matrix is a *column vector* (i.e. an $n \times 1$ matrix) of a suitable length.

Column vectors

One case that occurs frequently is when the second matrix is a *column vector* (i.e. an $n \times 1$ matrix) of a suitable length. For example,

Column vectors

One case that occurs frequently is when the second matrix is a *column vector* (i.e. an $n \times 1$ matrix) of a suitable length. For example,

$$\begin{pmatrix} 1 & 3 & 1 \\ 2 & 0 & -1 \end{pmatrix} \begin{pmatrix} 3 \\ 2 \\ 2 \end{pmatrix} =$$

Column vectors

One case that occurs frequently is when the second matrix is a *column vector* (i.e. an $n \times 1$ matrix) of a suitable length. For example,

$$\begin{pmatrix} 1 & 3 & 1 \\ 2 & 0 & -1 \end{pmatrix} \begin{pmatrix} 3 \\ 2 \\ 2 \end{pmatrix} = \begin{pmatrix} 1.3 + 3.2 + 1.2 \\ 2.3 + 0.2 + (-1).2 \end{pmatrix} =$$

Column vectors

One case that occurs frequently is when the second matrix is a *column vector* (i.e. an $n \times 1$ matrix) of a suitable length. For example,

$$\begin{pmatrix} 1 & 3 & 1 \\ 2 & 0 & -1 \end{pmatrix} \begin{pmatrix} 3 \\ 2 \\ 2 \end{pmatrix} = \begin{pmatrix} 1.3 + 3.2 + 1.2 \\ 2.3 + 0.2 + (-1).2 \end{pmatrix} = \begin{pmatrix} 11 \\ 4 \end{pmatrix}.$$

Column vectors

One case that occurs frequently is when the second matrix is a *column vector* (i.e. an $n \times 1$ matrix) of a suitable length. For example,

$$\begin{pmatrix} 1 & 3 & 1 \\ 2 & 0 & -1 \end{pmatrix} \begin{pmatrix} 3 \\ 2 \\ 2 \end{pmatrix} = \begin{pmatrix} 1.3 + 3.2 + 1.2 \\ 2.3 + 0.2 + (-1).2 \end{pmatrix} = \begin{pmatrix} 11 \\ 4 \end{pmatrix}.$$

The result will always be a column vector,

Column vectors

One case that occurs frequently is when the second matrix is a *column vector* (i.e. an $n \times 1$ matrix) of a suitable length. For example,

$$\begin{pmatrix} 1 & 3 & 1 \\ 2 & 0 & -1 \end{pmatrix} \begin{pmatrix} 3 \\ 2 \\ 2 \end{pmatrix} = \begin{pmatrix} 1.3 + 3.2 + 1.2 \\ 2.3 + 0.2 + (-1).2 \end{pmatrix} = \begin{pmatrix} 11 \\ 4 \end{pmatrix}.$$

The result will always be a column vector, although not in general with the same length.

Another thing to notice is that multiplication by the identity matrix

Another thing to notice is that multiplication by the identity matrix (of the correct size)

Another thing to notice is that multiplication by the identity matrix (of the correct size) will leave the other matrix unchanged.

Another thing to notice is that multiplication by the identity matrix (of the correct size) will leave the other matrix unchanged. For example,

Another thing to notice is that multiplication by the identity matrix (of the correct size) will leave the other matrix unchanged. For example,

$$\begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 3 & 1 \\ 2 & 0 & -1 \end{pmatrix} = \begin{pmatrix} 1.1 + 0.2 & 1.3 + 0.0 & 1.1 + 0.(-1) \\ 0.1 + 1.2 & 0.3 + 1.0 & 0.1 + 1.(-1) \end{pmatrix}$$

Another thing to notice is that multiplication by the identity matrix (of the correct size) will leave the other matrix unchanged. For example,

$$\begin{aligned} \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} 1 & 3 & 1 \\ 2 & 0 & -1 \end{pmatrix} &= \begin{pmatrix} 1.1 + 0.2 & 1.3 + 0.0 & 1.1 + 0.(-1) \\ 0.1 + 1.2 & 0.3 + 1.0 & 0.1 + 1.(-1) \end{pmatrix} \\ &= \begin{pmatrix} 1 & 3 & 1 \\ 2 & 0 & -1 \end{pmatrix}. \end{aligned}$$

Activity. Working in groups of two or three, in each case find a matrix A such that

$$(i) \quad A \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} x \cos a - y \sin a \\ x \sin a + y \cos a \end{pmatrix}.$$

$$(ii) \quad A \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} x - 2y + z \\ 2y - 8z \\ -4x + 5y + 9z \end{pmatrix}.$$

$$(iii) \quad A \begin{pmatrix} x_{\text{urban}} \\ x_{\text{suburban}} \end{pmatrix} = \begin{pmatrix} 0.95x_{\text{urban}} + 0.03x_{\text{suburban}} \\ 0.05x_{\text{urban}} + 0.97x_{\text{suburban}} \end{pmatrix}.$$

$$(i) \quad A = \begin{pmatrix} \cos a & -\sin a \\ \sin a & \cos a \end{pmatrix}.$$

(i) $A = \begin{pmatrix} \cos a & -\sin a \\ \sin a & \cos a \end{pmatrix}$.

This matrix corresponds to rotation of the plane through an angle a :

(i) $A = \begin{pmatrix} \cos a & -\sin a \\ \sin a & \cos a \end{pmatrix}$.

This matrix corresponds to rotation of the plane through an angle a : given a point (x, y) , calculating

$$A \begin{pmatrix} x \\ y \end{pmatrix}$$

gives the coordinates of where it ends up after the rotation.

$$(ii) \quad A = \begin{pmatrix} 1 & -2 & 1 \\ 0 & 2 & -8 \\ -4 & 5 & 9 \end{pmatrix}.$$

$$(ii) \quad A = \begin{pmatrix} 1 & -2 & 1 \\ 0 & 2 & -8 \\ -4 & 5 & 9 \end{pmatrix}.$$

Notice that the equations in the example at the start of the lecture correspond to the matrix equation

$$A \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 0 \\ 8 \\ -9 \end{pmatrix}.$$

$$(ii) A = \begin{pmatrix} 1 & -2 & 1 \\ 0 & 2 & -8 \\ -4 & 5 & 9 \end{pmatrix}.$$

Notice that the equations in the example at the start of the lecture correspond to the matrix equation

$$A \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 0 \\ 8 \\ -9 \end{pmatrix}.$$

The solution is then

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} = A^{-1} \begin{pmatrix} 0 \\ 8 \\ -9 \end{pmatrix}.$$

(iii) $A = \begin{pmatrix} 0.95 & 0.03 \\ 0.05 & 0.97 \end{pmatrix}$.

(iii) $A = \begin{pmatrix} 0.95 & 0.03 \\ 0.05 & 0.97 \end{pmatrix}$.

In the example at the beginning of the lecture,

$$A \begin{pmatrix} 600,000 \\ 400,000 \end{pmatrix}$$

will give the amount of people in the urban and suburban areas after one year.

(iii) $A = \begin{pmatrix} 0.95 & 0.03 \\ 0.05 & 0.97 \end{pmatrix}$.

In the example at the beginning of the lecture,

$$A \begin{pmatrix} 600,000 \\ 400,000 \end{pmatrix}$$

will give the amount of people in the urban and suburban areas after one year. Multiplying by A repeatedly means the populations after 25 years will be given by

$$A^{25} \begin{pmatrix} 600,000 \\ 400,000 \end{pmatrix}.$$

And finally. . .

Reminders:

- email address mas-engineering@sheffield.ac.uk
- website <http://engmaths.group.shef.ac.uk/mas156>
(also accessible through MOLE).